

ON TWO EFFICIENT ROOT-SOLVERS WITH MEMORY

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THE AIM OF COMMUNICATION

- The aim of this communication is the construction, efficiency analysis and numerical testing of two new one-step methods with memory for solving nonlinear equations of the form $f(x) = 0$, where f is a function of a real or complex variable.
- The presented methods possess very high efficiency and can be used as predictor steps in constructing multipoint methods.

ONE-STEP METHODS

Newton method (N): $x_{k+1} = x_k - \frac{f(x_k)}{f'(x_k)},$

Steffensen method: $x_{k+1} = x_k - \frac{f(x_k)^2}{f(x_k + f(x_k)) - f(x_k)},$

Traub-Steffensen method ($T - S$):

$$x_{k+1} = x_k - \frac{\gamma f(x_k)^2}{f(x_k + \gamma f(x_k)) - f(x_k)},$$

Halley method: $x_{k+1} = x_k - \frac{f(x_k)}{f'(x_k) - \frac{f''(x_k)f(x_k)}{2f'(x_k)}}.$

ONE-STEP METHODS WITH MEMORY (EARLY WORKS)

Traub-Steffensen's method with memory ($T - S M$) :

$$\left\{ \begin{array}{l} \gamma_0 \text{ is given, } \quad \gamma_k = -\frac{x_k - x_{k-1}}{f(x_k) - f(x_{k-1})} \text{ for } k \geq 1, \\ x_{k+1} = x_k - \frac{\gamma_k f(x_k)^2}{f(x_k + \gamma_k f(x_k)) - f(x_k)}, \quad (k = 0, 1, \dots) \end{array} \right.$$

with the order of convergence at least $1 + \sqrt{2} \approx 2.414$.

ONE-STEP METHODS WITH MEMORY (EARLY WORKS)**(CONTINUATION)**

Traub's method with memory ($T M$) of order no less than $1 + \sqrt{3} \approx 2.732$

$$\left\{ \begin{array}{l} p_0 \text{ is given, } p_k = -\frac{H_3''(x_k)}{2f'(x_k)} \text{ for } k \geq 1, \\ x_{k+1} = x_k - \frac{f(x_k)}{f'(x_k) + p_k f(x_k)}, \quad (k = 0, 1, \dots), \end{array} \right.$$

where

$$H_3''(x_k) = \frac{2}{x_k - x_{k-1}} (2f'(x_k) + f'(x_{k-1}) - 3f[x_k, x_{k-1}]).$$

RECENT RESULTS

M. S. Petković J. Džunić, L. D. Petković, A family of two-point methods with memory for solving nonlinear equations, *Appl. Anal. Discrete Math.* 5 (2011), 298–317.

J. Džunić, M. S. Petković, L. D. Petković, Three-point methods with and without memory for solving nonlinear equations, *Appl. Math. Comput.* 218 (2012), 4917–4927.

J. Džunić, M. S. Petković, On generalized multipoint root-solvers with memory, *J. Comput. Appl. Math.* 236 (2012) 2909–2920.

MODIFIED STEFFENSEN METHOD

Let α be a simple real zero of a real function $f : D \subset \mathbb{R} \rightarrow \mathbb{R}$ and let x_0 be an initial approximation to α , and $p \in \mathbb{R}$ a parameter. Steffensen method modification:

$$\begin{cases} w_k = x_k + \gamma f(x_k), \\ x_{k+1} = x_k - \frac{f(x_k)}{f[w_k, x_k] + pf(w_k)} \end{cases} \quad (k = 0, 1, \dots), \quad (1)$$

Introduce notation $c_2 = f''(\alpha)/(2f'(\alpha))$, $\varepsilon_k = x_k - \alpha$ and $\varepsilon_{k,w} = w_k - \alpha$. Error relation of the method **(1)**:

$$\varepsilon_{k+1} \sim (1 + \gamma f'(\alpha))(c_2 + p)\varepsilon_k^2,$$

plays the key role in convergence acceleration.

ACCELERATION OF THE MODIFIED STEFFENSEN METHOD

Minimizing of terms $1 + \gamma f'(\alpha)$ and $c_2 + p$ is obtained by the following models:

$$\text{Model (I)} \quad \left\{ \begin{array}{l} \gamma_k = -\frac{1}{f[x_k, w_{k-1}]} = -\frac{1}{N_1'(x_k)}, \\ p_k = -\frac{f[w_k, x_k, w_{k-1}]}{f[w_k, x_k]} = -\frac{N_2''(w_k)}{2f[w_k, x_k]}, \end{array} \right. \quad (2)$$

where

$$N_1(\tau) = N_1(\tau; x_k, w_{k-1}) \quad \text{and} \quad N_2(\tau) = N_2(\tau; w_k, x_k, w_{k-1});$$

ACCELERATION OF THE MODIFIED STEFFENSEN METHOD**(CONTINUATION)**

$$\text{Model (II)} \quad \left\{ \begin{array}{l} \gamma_k = -\frac{1}{N_2'(x_k)}, \\ p_k = -\frac{N_3''(w_k)}{2f[w_k, x_k]}, \end{array} \right. \quad (3)$$

where

$$N_2(\tau) = N_2(\tau; x_k, w_{k-1}, x_{k-1}) \text{ and}$$

$$N_3(\tau) = N_3(\tau; w_k, x_k, w_{k-1}, x_{k-1});$$

NEW METHOD WITH MEMORY OF STEFFENSEN TYPE

After substituting constant parameters γ and p by γ_k and p_k in each iteration step, we obtain

$$\left\{ \begin{array}{l} \gamma_0, p_0 \text{ are given,} \\ \gamma_k = -\frac{1}{N'_m(x_k)}, \quad p_k = -\frac{N''_{m+1}(w_k)}{2f[w_k, x_k]}, \quad (m = 1, 2) \text{ for } k \geq 1, \\ x_{k+1} = x_k - \frac{f(x_k)}{f[w_k, x_k] + p_k f(w_k)} \quad (k = 0, 1, \dots). \end{array} \right. \quad (4)$$

CONVERGENCE THEOREM I

Theorem 1. *If an initial approximation \mathbf{x}_0 is sufficiently close to a zero α of \mathbf{f} , then the order of convergence of the Steffensen-like method with memory (4) is at least three if γ_k and \mathbf{p}_k are calculated by (2). If formulae (3) are used for calculating γ_k and \mathbf{p}_k , then the order $\frac{1}{2}(3 + \sqrt{17}) \approx 3.56$ is achieved.*

MODIFIED NEWTON METHOD

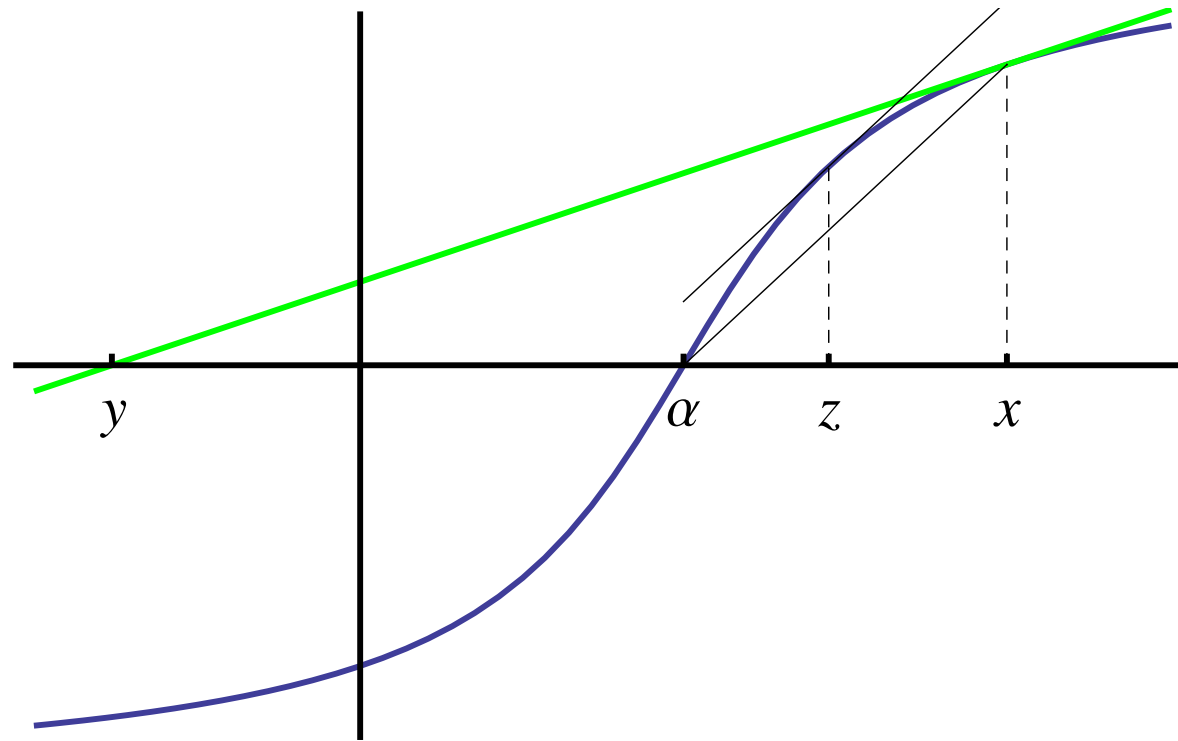


FIGURE 1 Geometric interpretation for the new method

MODIFIED NEWTON METHOD

New approximation for the sought simple zero α calculated by

$$\begin{cases} w_k = x_k + \gamma f(x_k), \\ x_{k+1} = x_k - \frac{f(x_k)}{f'(w_k)} \end{cases} \quad (5)$$

has an error relation of the form

$$\varepsilon_{k+1} \sim c_2(1 + 2\gamma f'(\alpha))\varepsilon_k^2.$$

ACCELERATION OF THE MODIFIED NEWTON METHOD

Formulae for accelerating modified Newton method are

$$\gamma_k = -\frac{1}{2f'(w_{k-1})} \quad \text{Model (I),} \quad (6)$$

$$\gamma_k = -\frac{1}{2f[x_k, x_{k-1}]} \quad \text{Model (II),} \quad (7)$$

$$\gamma_k = -\frac{1}{2(f'(w_{k-1}) + 2a_2(x_k - w_{k-1}))} \quad \text{Model (III),} \quad (8)$$

ACCELERATION OF THE MODIFIED NEWTON METHOD**(CONTINUATION)**

where

$$P(t) = a_0 + a_1(t - x_k) + a_2(t - x_k)(t - w_{k-1})$$

is the interpolating polynomial that satisfies the interpolation conditions

$$P(x_k) = f(x_k), \quad P'(w_{k-1}) = f'(w_{k-1}), \quad P(x_{k-1}) = f(x_{k-1}).$$

NEW METHOD WITH MEMORY OF NEWTON TYPE

Substituting γ by γ_k calculated by one of methods I–III we obtain

$$\left\{ \begin{array}{l} \gamma_0, \text{ is given, } \gamma_k \text{ is calculated by one of (6)–(8) for } k \geq 1, \\ w_k = x_k + \gamma_k f(x_k), \\ x_{k+1} = x_k - \frac{f(x_k)}{f'(w_k)} \quad (k = 0, 1, \dots). \end{array} \right. \quad (9)$$

CONVERGENCE THEOREMS FOR THE MODIFIED NEWTON METHOD

Theorem 2. *If an initial approximation \mathbf{x}_0 is sufficiently close to a zero α of \mathbf{f} , then the order of convergence of the modified Newton method with memory (9), where γ_k is calculated by (6) or (7), is $1 + \sqrt{2} \approx 2.414$.*

Theorem 3. *When an initial approximation \mathbf{x}_0 is sufficiently close to the sought simple zero α of \mathbf{f} , the order of convergence of the modified Newton method with memory (9) \wedge (8) is not less than $1 + \sqrt{2} \approx 2.414$, and with appropriate distribution of approximations it is not less than $1 + \sqrt{3} \approx 2.732$.*

COMPUTATIONAL ASPECTS

Computational efficiency of any iterative zero-finding method is closely connected to the features such as

- the number of necessary numerical operations in computing zeros with the required accuracy,
- the convergence speed,
- processor time of a computer, etc.

COMPUTATIONAL ASPECTS

Coefficient of efficiency is given by

$$E(IM) = r^{1/\theta}, \quad (10)$$

where

r is the order of convergence of the iterative method (IM), and

θ is the computational cost (number of function evaluations per iteration).

COMPUTATIONAL ASPECTS

Using formula (10) we find

$$E(N) = E(T - S) = E(\mathbf{1}) = E(\mathbf{5}) = 2^{1/2} \approx 1.414,$$

$$E(\mathbf{4} \wedge \mathbf{2}) = 3^{1/2} \approx 1.732,$$

$$E(\mathbf{4} \wedge \mathbf{3}) = \left(\frac{1}{2}(3 + \sqrt{17}) \right)^{1/2} \approx 1.887,$$

$$E(T - S \ M) = (1 + \sqrt{2})^{1/2} \approx 1.554,$$

$$E(T \ M) = E(\mathbf{9}) = (1 + \sqrt{3})^{1/2} \approx 1.653.$$

Computational efficiency of any optimal three-step scheme (IM) is

$$E(IM) = 8^{1/4} \approx 1.682,$$

NUMERICAL EXAMPLES

We have tested the new methods (1), (4), (5) and (9), and the methods (N), ($T - S$) and ($T M$)

We applied the programming package **Mathematica** with multiprecision arithmetic based on the GNU multiprecision package GMP developed by Granlund

T. Granlund, GNU MP; The GNU multiple precision arithmetic library, edition 5.0.1 (2010).

Test functions:

$$f_1(x) = e^{-x^2+x+2} - \cos(x+1) + x^3 + 1, \quad \alpha = -1, \quad x_0 = -1.7,$$

$$\gamma_0 = -0.01, \quad p_0 = -0.01,$$

$$f_2(x) = (x-1)(x^6 + x^{-6} + 4) \sin x^2, \quad \alpha = 1, \quad x_0 = 1.5,$$

$$\gamma_0 = -0.05, \quad p_0 = 0,$$

$$f_3(x) = \prod_{i=1}^{12} (x - i), \quad \alpha = 8, \quad x_0 = 8.33, \quad \gamma_0 = -0.1, \quad p_0 = 0,$$

$$f_4(x) = x + \sin x + \frac{1}{x} - 1 + 2i, \quad \alpha \approx 0.2886 - i1.2422,$$

$$x_0 = -1 - 3i \quad (i = \sqrt{-1}), \quad \gamma_0 = -0.05, \quad p_0 = -0.05.$$

NUMERICAL EXAMPLES

The tables contain the computational order of convergence r_c evaluated by the following formula

$$r_c = \frac{\log |f(x_k)/f(x_{k-1})|}{\log |f(x_{k-1})/f(x_{k-2})|}. \quad (11)$$

The errors $|x_k - \alpha|$ of approximations to the zeros are given in the form $A(-h)$, which denotes $A \times 10^{-h}$.

Methods	$ x_1 - \alpha $	$ x_2 - \alpha $	$ x_3 - \alpha $	$ x_4 - \alpha $	r_c (11)
$(T - S)$	1.37(-1)	9.28(-4)	1.36(-7)	2.88(-15)	2.00
(1)	1.40(-1)	7.35(-4)	8.00(-8)	9.41(-16)	2.00
(4)^(2)	1.37(-1)	5.81(-4)	4.75(-12)	2.87(-36)	3.00
(4)^(3)	1.37(-1)	1.51(-4)	8.34(-15)	2.23(-51)	3.57
(N)	1.49(-1)	8.40(-4)	1.18(-7)	2.33(-15)	2.00
$(T M)$	1.49(-1)	1.98(-3)	8.96(-9)	3.48(-23)	2.70
(5)	1.24(-1)	9.16(-4)	1.24(-7)	2.24(-15)	2.00
(9)^(6)	1.24(-1)	5.25(-4)	8.73(-10)	1.09(-23)	2.41
(9)^(7)	1.24(-1)	3.67(-4)	3.26(-10)	1.09(-24)	2.38
(9)^(8)	1.24(-1)	1.33(-5)	4.47(-13)	4.21(-35)	2.95

Table 1: One-point method without/with memory, test function f_1

Methods	$ x_1 - \alpha $	$ x_2 - \alpha $	$ x_3 - \alpha $	$ x_4 - \alpha $	r_c (11)
$(T - S)$	1.04(-1)	1.19(-2)	1.42(-4)	1.94(-8)	2.00
(1)	1.00(-1)	1.06(-2)	1.03(-4)	9.35(-9)	2.00
(4) [^] (2)	1.04(-1)	1.26(-3)	1.04(-8)	1.97(-24)	3.09
(4) [^] (3)	1.04(-1)	2.65(-4)	1.55(-12)	4.31(-42)	3.59
(N)	9.98(-2)	1.57(-2)	3.37(-4)	1.46(-7)	2.01
$(T - M)$	9.98(-2)	2.90(-2)	8.56(-5)	1.16(-11)	2.73
(5)	8.44(-2)	2.99(-3)	5.73(-6)	2.09(-11)	2.00
(9) [^] (6)	8.44(-2)	3.03(-3)	1.51(-6)	9.98(-15)	2.47
(9) [^] (7)	8.44(-2)	3.10(-3)	1.05(-6)	5.71(-15)	2.38
(9) [^] (8)	8.44(-2)	3.14(-3)	7.04(-7)	1.53(-16)	2.64

Table 2: One-point method without/with memory, test function f_2

Methods	$ x_1 - \alpha $	$ x_2 - \alpha $	$ x_3 - \alpha $	$ x_4 - \alpha $	r_c (11)
$(T - S)$	div.				
(1) for all p_0	div.				
(4) \wedge (2)	3.30(-1)	3.30(-1)	1.29(-2)	7.64(-7)	3.00
(4) \wedge (3)	3.30(-1)	3.30(-1)	1.62(-2)	6.92(-8)	4.11
(N)	7.22(-2)	3.97(-3)	7.84(-6)	3.14(-11)	2.00
$(T M)$	div.				
(5)	div.				
(9) \wedge (6)	7.22(-2)	6.84(-4)	8.53(-9)	1.25(-20)	2.41
(9) \wedge (7)	7.22(-2)	1.13(-5)	2.93(-12)	2.52(-29)	2.59
(9) \wedge (8)	7.22(-2)	5.28(-4)	5.51(-10)	3.43(-24)	2.37

Table 3: One-point method without/with memory, test function f_3

Methods	$ x_1 - \alpha $	$ x_2 - \alpha $	$ x_3 - \alpha $	$ x_4 - \alpha $	r_c (11)
$(T - S)$	9.69(-1)	1.77(-1)	3.67(-3)	2.31(-6)	1.89
(1)	9.38(-1)	1.54(-1)	3.72(-3)	2.85(-6)	1.92
(4)^(2)	9.38(-1)	8.37(-2)	3.32(-5)	1.06(-15)	3.08
(4)^(3)	9.38(-1)	1.95(-2)	1.15(-10)	2.26(-33)	2.76
(N)	1.29(0)	4.95(-1)	1.95(-2)	7.51(-5)	1.70
$(T M)$	1.34(0)	1.48(-1)	3.05(-4)	1.88(-10)	2.32
(5)	7.29(-1)	6.71(-2)	5.61(-4)	4.30(-8)	1.97
(9)^(6)	7.29(-1)	6.27(-2)	1.51(-4)	6.79(-11)	2.42
(9)^(7)	7.29(-1)	5.78(-2)	9.29(-5)	2.00(-11)	2.38
(9)^(8)	7.29(-1)	6.05(-2)	1.08(-4)	3.24(-12)	2.74

Table 4: One-point method without/with memory, test function f_4

THANK YOU FOR YOUR ATTENTION!